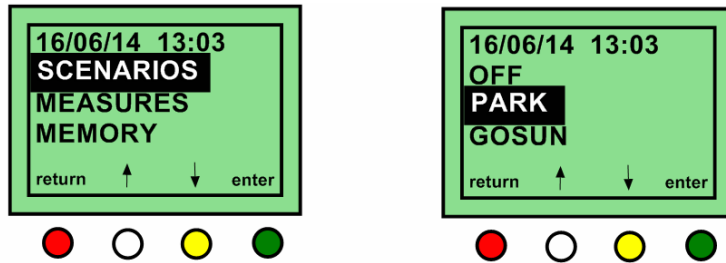
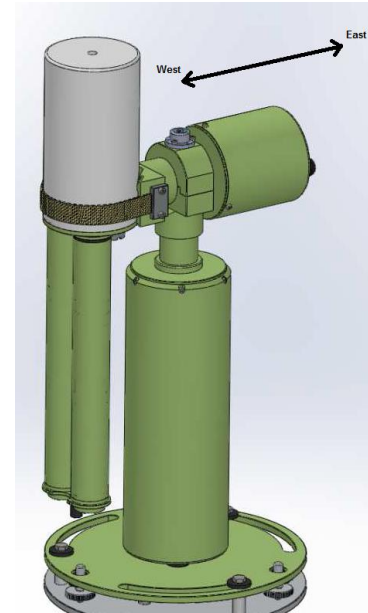


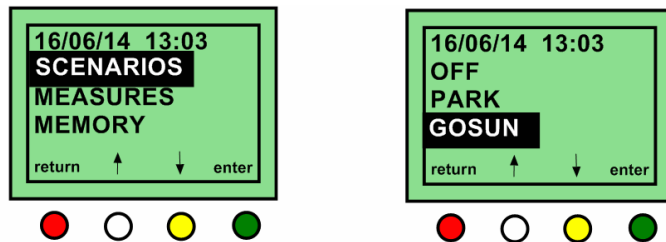
1. Perform a **"PARK"** scenario in the control box menu. The robot will find its home position. The collimator should return to pointing down. Set the horizontal robot axis in the East-West direction by manually turning the whole base of the robot.



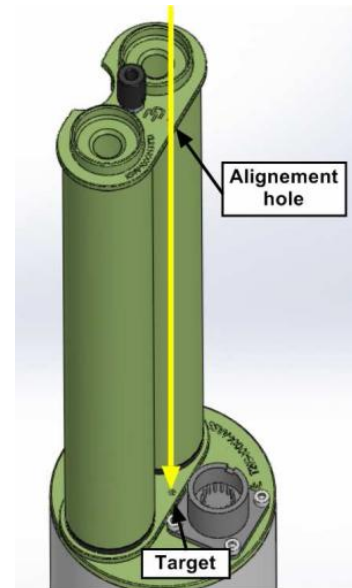
Select SCENARIOS then PARK and validate with the green button



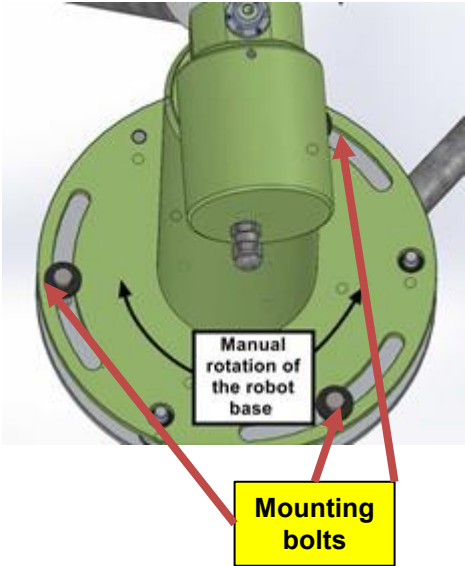
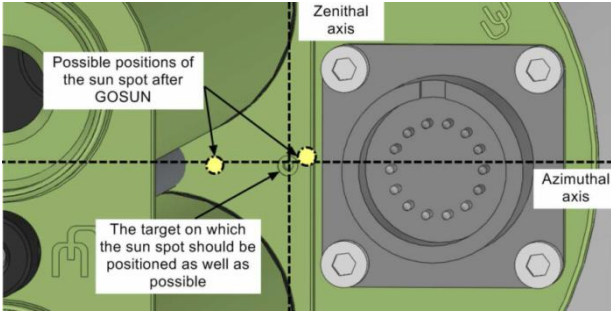
2. Perform a **"GOSUN"** scenario in the control box menu. The sensor head will point to the sun.



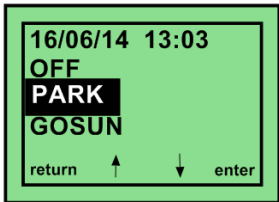
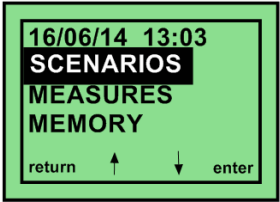
Select SCENARIOS then GOSUN and validate with the green button



3. After a “GOSUN” scenario loosen the 3 mounting bolts and rotate the base of the robot until the sun spot lines up close to the target. The sun spot may not be centered on the target but should be closer than 4mm. (see page 4 for additional pictures)

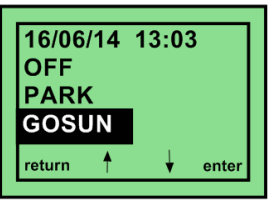
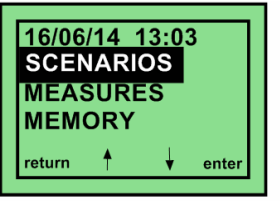


4. Perform a “PARK” scenario in the control box menu again. The robot will find its home position.



Select SCENARIOS then PARK and validate with the green button

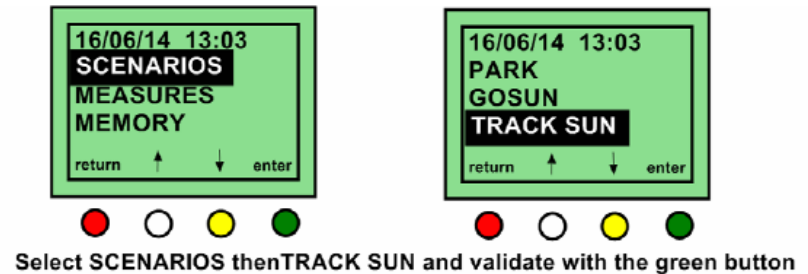
5. Perform a “GOSUN” scenario in the control box menu. The sensor head will point to the sun.



Select SCENARIOS then GOSUN and validate with the green button

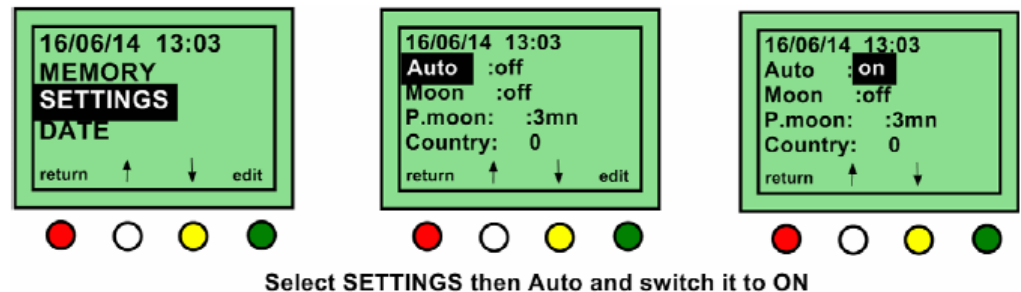
6. Perform a **“TRACK SUN”** scenario in the Control box menu. The sun spot should automatically align to the target at base of collimator. (see page 4 for additional pictures)

**Note:** If it doesn't align correctly, check and reseal connections



7. When the sun spot aligns correctly, repeat step 4, 5 and 6 once or twice to validate the photometer behavior.

8. Set the photometer in automatic mode.



**GOSUN**

**Target**

**Sun Spot**

**TRACK**

**SUN SPOT ALIGNED  
ON TARGET**

